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# Exit and occupation times for Brownian motion on graphs with general drift and diffusion constant 

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#### Abstract

We consider a particle diffusing along the links of a general graph possessing some absorbing vertices. The particle, with a spatially dependent diffusion constant $D(x)$, is subjected to a drift $U(x)$ that is defined in every point of each link. We establish the boundary conditions to be used at the vertices and we derive general expressions for the average time spent on a part of the graph before absorption and, also, for the Laplace transform of the joint law of the occupation times. Exit times distributions and splitting probabilities are also studied and several examples are discussed.


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## 1. Introduction

For many years, graphs have interested physicists as well as mathematicians. For instance, equilibrium statistical physics widely uses model systems defined on lattices, the most popular being certainly the Ising model [1]. On another hand, in solid-state physics, tight-binding models (see, for instance, [2]) involve discretized versions of Schrödinger operators on graphs. For all those models, the thermodynamic properties of the system heavily depend on geometrical characteristics of the lattice such as the connectivity and the dimensionality of the embedding space. However, in general, they do not depend explicitly on the lengths of the edges. Random walks on graphs, where a particle hops from one vertex to one of its nearest neighbours, have also been studied by considering discrete Laplacian operators on graphs [3].

Such Laplacian operators can also be useful if they are defined on each link of the graph. For example, in the context of organic molecules [4], they can describe free electrons on networks made of one-dimensional wires. Many other applications can be found in the physical literature. Let us simply cite the study of vibrational properties of fractal structures such as the Sierpinski gasket [5] or the investigation of quantum transport in mesoscopic
physics [6, 7]. Weakly disordered systems can also be studied in this context [8]. It appears that weak localization corrections in the presence of an eventual magnetic field are related to a spectral determinant on the graph. This last quantity is actually of central importance and interesting by itself $[9,10]$. In particular, it allows us to recover a trace formula that was first derived by Roth [11]. Moreover, the spectral determinant, when computed with generalized boundary conditions at the vertices, is useful to enumerate constrained random walks on a general graph [12], a problem that has been addressed many times in the mathematical literature [13].

Brownian motion on graphs is also worthwhile to be investigated from, both, the physical and mathematical viewpoints. For instance, the probability distribution of the time spent on a link (the so-called occupation time) was first studied by Levy [14], who considered the time spent on an infinite half-line by a one-dimensional Brownian motion stopped at some time $t$. This work allowed Levy to discover in 1939 one of his famous arc-sine laws [15]. Since that time, this result has been generalized to a star graph [16] and also to a quite general graph [17]. Local time distributions have also been obtained in [18].

It was pointed out a long time that first-passage times and, more generally, occupation times are of special interest in the context of reaction-diffusion processes [19, 20]. Computations of such quantities in the presence of a constant external field have already been performed for one-dimensional systems with absorbing points (see, for example, [21]). This was done with the help of a linear Fokker-Planck equation [19, 22].

The purpose of the present work is to extend those results on a general graph with some absorbing vertices. We will consider a Brownian particle diffusing with a spatially dependent diffusion constant and subjected to a drift that is defined in every point of each link. The paper is organized as follows. In section 2, we present the notations that will be used throughout the paper. We discuss the boundary conditions to be used at each vertex in section 3 and, also, in the appendices. More precisely, we analyse in details specific graphs in appendices A and B. The obtained results allow us to deal with a general graph in appendix C. Section 4 is devoted to the computation of the average time spent, before absorption, by a Brownian particle on a part of the graph. In this section, we also calculate the Laplace transform of the joint law of the occupation times on each link. In the following section, we present additional results, especially concerning conditional and splitting probabilities. Various examples are discussed all along the different sections. Finally, a brief summary is given in section 6.

## 2. Definitions and notations

Let us consider a general graph $\mathcal{G}$ made of $V$ vertices linked by $B$ bonds of finite lengths. On each bond $[\alpha \beta]$, of length $l_{\alpha \beta}$, we define the coordinate $x_{\alpha \beta}$ that runs from 0 (vertex $\alpha$ ) to $l_{\alpha \beta}$ (vertex $\beta$ ). (We have, of course, $x_{\beta \alpha}=l_{\alpha \beta}-x_{\alpha \beta}$.)

Moreover, we suppose that, among all the vertices, $N$ of them are absorbing (a particle gets trapped if it reaches such a vertex).

We will study the motion on $\mathcal{G}$ of a Brownian particle that starts at $t=0$ from some non-absorbing point $x$. The particle, with a spatially dependent diffusion constant $D(x)$, is subjected to a drift $U(x)$ defined on the bonds of $\mathcal{G}$. More precisely, $D(x)$ and $U(x)$ are differentiable functions of $x$ on each link. In particular, on each link $[\alpha \beta$ ], the following limits $D_{(\alpha \beta)} \equiv \lim _{x_{\alpha \beta} \rightarrow 0} D\left(x_{\alpha \beta}\right), D_{(\alpha \beta)}^{\prime} \equiv \lim _{x_{\alpha \beta} \rightarrow 0} \frac{\partial}{\partial x_{\alpha \beta}} D\left(x_{\alpha \beta}\right), U_{(\alpha \beta)} \equiv \lim _{x_{\alpha \beta} \rightarrow 0} U\left(x_{\alpha \beta}\right), \ldots$, are well defined. Such notations will be used extensively throughout the paper.

The continuity properties of $D(x)$ and $U(x)$ at each vertex will be discussed in the following section.


Figure 1. The vertex $\alpha$ with its nearest neighbours $\beta_{i}, i=1, \ldots, m_{\alpha}$; each link is discretized with steps of lengths $\Delta x$.

We also specify the motion of the particle when it reaches some vertex $\alpha$. Let us call $\beta_{i}\left(i=1, \ldots, m_{\alpha}\right)$ the nearest neighbours of $\alpha$. We assume that the particle will come out towards $\beta_{i}$ with some arbitrary probability $p_{\alpha \beta_{i}}\left(\sum_{i} p_{\alpha \beta_{i}}=1\right.$-see [16] for a rigorous mathematical definition). Of course, $p_{\lambda \mu}=0$ if $\lambda$ is an absorbing vertex or if $[\lambda \mu]$ is not a bond of $\mathcal{G}$.

Let $P(y t \mid x 0)$ be the probability density to find the particle at point $y$ at time $t$ $(P(y 0 \mid x 0)=\delta(y-x))$. It satisfies on each link $[\alpha \beta]$ the backward and forward Fokker-Planck equations:
$\frac{\partial P\left(y t \mid x_{\alpha \beta} 0\right)}{\partial t}=D\left(x_{\alpha \beta} \frac{\partial^{2} P}{\partial x_{\alpha \beta}^{2}}-\frac{\partial U\left(x_{\alpha \beta}\right)}{\partial x_{\alpha \beta}} \frac{\partial P}{\partial x_{\alpha \beta}} \equiv L^{+}\left(x_{\alpha \beta}\right) P\left(y t \mid x_{\alpha \beta} 0\right)\right.$,
$\frac{\partial P\left(y_{\alpha \beta} t \mid x 0\right)}{\partial t}=\frac{\partial}{\partial y_{\alpha \beta}}\left[\frac{\partial}{\partial y_{\alpha \beta}}\left(D\left(y_{\alpha \beta}\right) P\right)+\frac{\partial U\left(y_{\alpha \beta}\right)}{\partial y_{\alpha \beta}} P\right] \equiv L\left(y_{\alpha \beta}\right) P\left(y_{\alpha \beta} t \mid x 0\right)$.
$P_{(\alpha \beta)}$ will mean $\lim _{x_{\alpha \beta} \rightarrow 0} P\left(y t \mid x_{\alpha \beta} 0\right)$ when we use the backward Fokker-Planck equation and $\lim _{y_{\alpha \beta} \rightarrow 0} P\left(y_{\alpha \beta} t \mid x 0\right)$ when we use the forward equation. The derivatives $P_{(\alpha \beta)}^{\prime}$ will be defined in a similar way.

## 3. Boundary conditions

Let us define the following two situations that can occur at some non-absorbing vertex $\alpha$ :
(A) : $\quad D(x)$ is continuous but $U(x)$ is not,
(B) : $U(x)$ is continuous but $D(x)$ is not.

The main purpose of this section is to establish the boundary conditions for $P$ and its derivatives that result from those discontinuities. We will not consider the case when both $U(x)$ and $D(x)$ are discontinuous at the same vertex because, in our opinion, it is ill defined.

### 3.1. Backward Fokker-Planck equation

Let us start by considering a graph $\mathcal{G}$ with $U(x)$ and $D(x)$ constant (standard Brownian motion). In figure 1, we display a given vertex $\alpha$ and its nearest neighbours $\beta_{i}, i=1, \ldots, m_{\alpha}$ on $\mathcal{G}$.

The transition probabilities from $\alpha, p_{\alpha} \beta_{i}$, are not supposed to be all equal. In order to establish the boundary conditions for the backward equation, we discretize all the links [ $\alpha \beta_{i}$ ] (and also the time) with steps of length $\Delta x$ (resp. $\Delta t$ ). It is easy to realize that

$$
\begin{align*}
& P(y,(N+1) \Delta t \mid \alpha, 0)=\sum_{i=1}^{m_{\alpha}} p_{\alpha \beta_{i}} P\left(y, N \Delta t \mid x_{i}, 0\right)  \tag{3}\\
& P\left(y,(N+1) \Delta t \mid x_{i}, 0\right)=\frac{1}{2} P(y, N \Delta t \mid \alpha, 0)+\frac{1}{2} P\left(y, N \Delta t \mid x_{i}^{\prime}, 0\right) \tag{4}
\end{align*}
$$

Taking the limit $\Delta x \rightarrow 0, \Delta t \propto(\Delta x)^{2}, N \rightarrow \infty, N \Delta t \equiv t$, we obtain, with (4),

$$
\begin{equation*}
P_{\left(\alpha \beta_{i}\right)}=\frac{1}{2} P(y, t \mid \alpha, 0)+\frac{1}{2} P_{\left(\alpha \beta_{i}\right)} . \tag{5}
\end{equation*}
$$

Thus

$$
\begin{equation*}
P_{\left(\alpha \beta_{i}\right)}=P(y, t \mid \alpha, 0) \quad \forall i . \tag{6}
\end{equation*}
$$

This shows that $P$ is continuous in $\alpha$.
Moreover, expanding (3) at order $\Delta x$, we get

$$
\begin{equation*}
P(y, t \mid \alpha, 0)=\sum_{i=1}^{m_{\alpha}} p_{\alpha \beta_{i}} P_{\left(\alpha \beta_{i}\right)}+\Delta x\left(\sum_{i=1}^{m_{\alpha}} p_{\alpha \beta_{i}} P_{\left(\alpha \beta_{i}\right)}^{\prime}\right)+O\left((\Delta x)^{2}\right) . \tag{7}
\end{equation*}
$$

With (6) and $\sum_{i=1}^{m_{\alpha}} p_{\alpha \beta_{i}}=1$, we show that

$$
\begin{equation*}
\sum_{i=1}^{m_{\alpha}} p_{\alpha \beta_{i}} P_{\left(\alpha \beta_{i}\right)}^{\prime}=0 \tag{8}
\end{equation*}
$$

On the other hand, for $p_{\alpha \beta_{1}}=p_{\alpha \beta_{2}}=\cdots=1 / m_{\alpha}$, equation (1) on the link $[\alpha \beta]$ can be written in the form

$$
\begin{align*}
& \frac{\partial}{\partial t}\left(\frac{1}{D\left(x_{\alpha \beta}\right)} \mathrm{e}^{-\Phi\left(x_{\alpha \beta}\right)} P\left(y t \mid x_{\alpha \beta} 0\right)\right)=\frac{\partial}{\partial x_{\alpha \beta}}\left(\mathrm{e}^{-\Phi\left(x_{\alpha \beta}\right)} \frac{\partial}{\partial x_{\alpha \beta}} P\left(y t \mid x_{\alpha \beta} 0\right)\right),  \tag{9}\\
& \text { with } \quad \Phi\left(x_{\alpha \beta}\right)=\int_{x_{0}}^{x_{\alpha \beta}} \frac{\partial U\left(x^{\prime}\right)}{\partial x^{\prime}} \frac{\mathrm{d} x^{\prime}}{D\left(x^{\prime}\right)} \tag{10}
\end{align*}
$$

where $x_{0}$ is some point on the graph.
We are aware that $\Phi\left(x_{\alpha \beta}\right)$ could be multi-valued because, in general, a graph is multiply connected ${ }^{3}$. However, this is not the case if we restrict ourselves to the vicinity of the given vertex $\alpha$. Choosing $x_{0}$ located on a link starting from $\alpha$, the integral in (10) involves in a unique way, at most, two integrals along links starting from $\alpha$. It is well defined if $U(x)$ and $D(x)$ are not discontinuous at the same point. So, with this definition of $\Phi\left(x_{\alpha \beta}\right)$, equation (9) is well suited to study the boundary conditions at vertex $\alpha$.

Let us consider the case (A).
We assume, first, that the $p_{\alpha \beta_{i}}$ 's are all equal.
Integrating (9) in the vicinity of $\alpha$, we get, with $D(x)$ continuous at $\alpha$,

$$
\begin{equation*}
\sum_{i=1}^{m_{\alpha}} \mathrm{e}^{-U_{\left(\alpha \beta_{i}\right)} / D(\alpha)} P_{\left(\alpha \beta_{i}\right)}^{\prime}=0 \tag{11}
\end{equation*}
$$

Moreover, $P$ must be continuous at $\alpha$ if we want the quantity $\mathrm{e}^{-\Phi} \frac{\partial P}{\partial x}$ to be properly defined.

[^0]In appendix A, those boundary conditions are directly established, for the Laplace transform of $P$, on a simple graph.

Still for the case (A), let us now assume that the $p_{\alpha \beta_{i}}$ 's are not all equal.
In appendix C, we establish the following boundary condition that must hold for a general graph:

$$
\begin{equation*}
\sum_{i=1}^{m_{\alpha}} p_{\alpha \beta_{i}} \mathrm{e}^{-U_{\left(\alpha \beta_{i}\right)} / D(\alpha)} P_{\left(\alpha \beta_{i}\right)}^{\prime}=0 \tag{12}
\end{equation*}
$$

We also show in this appendix that $P$ is continuous in $\alpha$.
Turning to the case (B), we can follow the same line as for (A) and use (9), and also appendices A and B.

Remark that, when the $p_{\alpha \beta_{i}}$ 's $\left(i=1,2, \ldots, m_{\alpha}\right)$ are all equal, the integration of (9) in the vicinity of $\alpha$ will not produce an exponential factor as in (11). This is because, this time, $U(x)$ is continuous in $\alpha$. This fact is confirmed by the direct computations performed in the appendices. Finally, with the $p_{\alpha \beta_{i}}$ 's not all equal, we get

$$
\begin{equation*}
\sum_{i=1}^{m_{\alpha}} p_{\alpha \beta_{i}} P_{\left(\alpha \beta_{i}\right)}^{\prime}=0 \tag{13}
\end{equation*}
$$

Moreover, $P$ is continuous for the cases (A) and (B).
In summary, for the backward Fokker-Planck equation, the condition on the derivatives can be written as

$$
\begin{align*}
\sum_{i=1}^{m_{\alpha}} p_{\alpha \beta_{i}}^{\prime} P_{\left(\alpha \beta_{i}\right)}^{\prime} & =0  \tag{14}\\
\text { with } \quad p_{\alpha \beta_{i}}^{\prime} & =p_{\alpha \beta_{i}} \mathrm{e}^{-\frac{U_{\left(\alpha \beta_{i}\right)}}{D(\alpha)}} \quad \text { case (A) }  \tag{15}\\
& =p_{\alpha \beta_{i}} \quad \text { case (B). } \tag{16}
\end{align*}
$$

This notation will prove especially useful in the following sections where the backward Fokker-Planck equation is widely used.

### 3.2. Forward Fokker-Planck equation

Coming back to figure 1 (with $x_{i}, x_{i}^{\prime}$ and $\Delta x$ replaced by $y_{i}, y_{i}^{\prime}$ and $\Delta y$ ), we consider the discretized version of the forward equation with $D(x)$ and $U(x)$ constant and, also, the $p_{\alpha \beta_{i}}$ 's not all equal. We have, on the link $\left[\alpha \beta_{i}\right]$,

$$
\begin{align*}
& P\left(y_{i},(N+1) \Delta t \mid x, 0\right)=p_{\alpha \beta_{i}} P(\alpha, N \Delta t \mid x, 0)+\frac{1}{2} P\left(y_{i}^{\prime}, N \Delta t \mid x, 0\right)  \tag{17}\\
& P(\alpha,(N+1) \Delta t \mid x, 0)=\frac{1}{2} \sum_{i=1}^{m_{\alpha}} P\left(y_{i}, N \Delta t \mid x, 0\right) \tag{18}
\end{align*}
$$

With the limit $\Delta y \rightarrow 0, \Delta t \propto(\Delta y)^{2}, N \rightarrow \infty, N \Delta t \equiv t$, (17) leads to

$$
\begin{equation*}
P_{\left(\alpha \beta_{i}\right)}=p_{\alpha \beta_{i}} P(\alpha, t \mid x, 0)+\frac{1}{2} P_{\left(\alpha \beta_{i}\right)} . \tag{19}
\end{equation*}
$$

Thus

$$
\begin{equation*}
\frac{P_{\left(\alpha \beta_{1}\right)}}{p_{\alpha \beta_{1}}}=\frac{P_{\left(\alpha \beta_{2}\right)}}{p_{\alpha \beta_{2}}}=\cdots=\frac{P_{\left(\alpha \beta_{m_{\alpha}}\right)}}{p_{\alpha \beta_{m_{\alpha}}}}=2 P(\alpha, t \mid x, 0) . \tag{20}
\end{equation*}
$$

We see that, in general, $P$ is not continuous in $\alpha$.

Moreover, expanding (18) at order $\Delta y$, we get

$$
\begin{equation*}
P(\alpha, t \mid x, 0)=\frac{1}{2} \sum_{i=1}^{m_{\alpha}}\left(P_{\left(\alpha \beta_{i}\right)}+\Delta y P_{\left(\alpha \beta_{i}\right)}^{\prime}\right)+O\left((\Delta y)^{2}\right) \tag{21}
\end{equation*}
$$

With (20), we can write

$$
\begin{equation*}
\sum_{i=1}^{m_{\alpha}} P_{\left(\alpha \beta_{i}\right)}^{\prime}=0 \tag{22}
\end{equation*}
$$

So, the current conservation does not involve the $p_{\alpha \beta_{i}}$ 's.
Now, for $p_{\alpha \beta_{1}}=p_{\alpha \beta_{2}}=\cdots=1 / m_{\alpha}$, equation (2) on the link $[\alpha \beta]$ can be written as

$$
\begin{align*}
& \frac{\partial}{\partial t} P\left(y_{\alpha \beta} t \mid x 0\right)=\frac{\partial}{\partial y_{\alpha \beta}}\left(\mathrm{e}^{-\Phi\left(y_{\alpha \beta}\right)} \frac{\partial}{\partial y_{\alpha \beta}}\left(D\left(y_{\alpha \beta}\right) \mathrm{e}^{\Phi\left(y_{\alpha \beta}\right)} P\left(y_{\alpha \beta} t \mid x 0\right)\right)\right),  \tag{23}\\
& \text { with } \quad \Phi\left(y_{\alpha \beta}\right)=\int_{y_{0}}^{y_{\alpha \beta}} \frac{\partial U\left(y^{\prime}\right)}{\partial y^{\prime}} \frac{\mathrm{d} y^{\prime}}{D\left(y^{\prime}\right)}, \tag{24}
\end{align*}
$$

where $y_{0}$ is some point on the graph; the discussion of section 3.1 for the definition of $\Phi$ is, of course, still relevant.

Following the same lines as in section 3.1, we get the current conservation at each nonabsorbing vertex $\alpha$ :

$$
\begin{equation*}
\sum_{i=1}^{m_{\alpha}}\left((D P)^{\prime}+U^{\prime} P\right)_{\left(\alpha \beta_{i}\right)}=0 \tag{25}
\end{equation*}
$$

if $\alpha$ is not the starting point. Otherwise, the right-hand side of (25) should be replaced by $-\delta(t)$. (25) does not depend on the continuity properties of $D(x)$ and $U(x)$.

Now, let us consider the case (A) and call $D(\alpha)$ the diffusion constant at $\alpha$.
When $p_{\alpha \beta_{1}}=\cdots=p_{\alpha \beta_{m_{\alpha}}}$, following [22], we can show that

$$
\begin{equation*}
\mathrm{e}^{\frac{U_{\left(\alpha \beta_{1}\right)}}{D(\alpha)}} P_{\left(\alpha \beta_{1}\right)}=\mathrm{e}^{\frac{U_{\left(\alpha \beta_{2}\right)}}{D(\alpha)}} P_{\left(\alpha \beta_{2}\right)}=\cdots=\mathrm{e}^{\frac{U_{\left(\alpha \beta_{n \alpha}\right)}}{D(\alpha)}} P_{\left(\alpha \beta_{m_{\alpha}}\right)} \tag{26}
\end{equation*}
$$

When the $p_{\alpha \beta_{i}}$ 's are not all equal, we use the same approach as that of appendix C and get

$$
\begin{equation*}
\text { (A): } \mathrm{e}^{\frac{U_{\left(\alpha \beta_{1}\right)}}{D(\alpha)}} \frac{P_{\left(\alpha \beta_{1}\right)}}{p_{\alpha \beta_{1}}}=\mathrm{e}^{\frac{U_{\left(\alpha \beta_{2}\right)}}{D(\alpha)}} \frac{P_{\left(\alpha \beta_{2}\right)}}{p_{\alpha \beta_{2}}}=\cdots=\mathrm{e}^{\frac{U_{\left(\alpha \beta_{m_{\alpha}}\right)}}{D(\alpha)}} \frac{P_{\left(\alpha \beta_{m_{\alpha}}\right)}}{p_{\alpha \beta_{m_{\alpha}}}} . \tag{27}
\end{equation*}
$$

Similarly, for the case (B), we obtain

$$
\begin{equation*}
\text { (B) : } \quad D_{\left(\alpha \beta_{1}\right)} \frac{P_{\left(\alpha \beta_{1}\right)}}{p_{\alpha \beta_{1}}}=D_{\left(\alpha \beta_{2}\right)} \frac{P_{\left(\alpha \beta_{2}\right)}}{p_{\alpha \beta_{2}}}=\cdots=D_{\left(\alpha \beta_{\left.m_{\alpha}\right)}\right)} \frac{P_{\left(\alpha \beta_{m_{\alpha}}\right)}}{p_{\alpha \beta_{m_{\alpha}}}} \text {. } \tag{28}
\end{equation*}
$$

When $p_{\alpha \beta_{1}}=\cdots=p_{\alpha \beta_{m_{\alpha}}}$, it is worth noting that conditions (27) and (28) are simply obtained if we want the quantity $\frac{\partial}{\partial y_{\alpha \beta}}\left(D\left(y_{\alpha \beta}\right) \mathrm{e}^{\Phi\left(y_{\alpha \beta}\right)} P\left(y_{\alpha \beta} t \mid x 0\right)\right)$, that appears in (23), to be properly defined.

In the following section, we will check the consistency of those boundary conditions (for the backward and the forward equations) on several examples.

## 4. Occupation times

### 4.1. Mean residence time

Let us first study the average time, $\langle\tau(x)\rangle$, spent on a part $\mathcal{D}$ of $\mathcal{G}$ by the particle before absorption. We have [21]

$$
\begin{equation*}
\langle\tau(x)\rangle=\int_{0}^{\infty} \mathrm{d} t \int_{\mathcal{D}} \mathrm{d} y P(y t \mid x 0) \tag{29}
\end{equation*}
$$

$(\langle\tau(x)\rangle$ is the sum of the infinitesimal residence times weighted by the probability of the presence in $\mathcal{D}$ at time $t$ ).

With (1), we get for $\langle\tau(x)\rangle$ the equation

$$
\begin{equation*}
L^{+}\left(x_{\alpha \beta}\right)\left\langle\tau\left(x_{\alpha \beta}\right)\right\rangle=-\mathbf{1}_{\mathcal{D}}\left(x_{\alpha \beta}\right) \tag{30}
\end{equation*}
$$

$\mathbf{1}_{\mathcal{D}}(x)$ is the characteristic function of the domain $\mathcal{D}: \mathbf{1}_{\mathcal{D}}(x)=1$ if $x \in \mathcal{D},=0$ otherwise.
The solution writes

$$
\begin{equation*}
\left\langle\tau\left(x_{\alpha \beta}\right)\right\rangle=\int_{0}^{x_{\alpha \beta}} \mathrm{d} u_{\alpha \beta} \phi\left(u_{\alpha \beta}\right)+A_{\alpha \beta} \int_{0}^{x_{\alpha \beta}} \mathrm{d} u_{\alpha \beta} I\left(u_{\alpha \beta}\right)+B_{\alpha \beta}, \tag{31}
\end{equation*}
$$

with

$$
\begin{align*}
& \phi\left(x_{\alpha \beta}\right)=-I\left(x_{\alpha \beta}\right)\left(\int_{0}^{x_{\alpha \beta}} \frac{\mathrm{d} z_{\alpha \beta}}{D\left(z_{\alpha \beta}\right)} \frac{\mathbf{1}_{\mathcal{D}}\left(z_{\alpha \beta}\right)}{I\left(z_{\alpha \beta}\right)}\right)  \tag{32}\\
& I\left(x_{\alpha \beta}\right)=\exp \left(\int_{0}^{x_{\alpha \beta}} \frac{\mathrm{d} z_{\alpha \beta}}{D\left(z_{\alpha \beta}\right)} \frac{\partial U}{\partial z_{\alpha \beta}}\right) . \tag{33}
\end{align*}
$$

The constants $A_{\alpha \beta}$ and $B_{\alpha \beta}$ are determined by imposing the boundary conditions at each vertex. Continuity implies

$$
\begin{align*}
& \lim _{x_{\alpha \beta_{i}} \rightarrow 0}\left\langle\tau\left(x_{\alpha \beta_{i}}\right)\right\rangle \equiv\left\langle\tau_{\alpha}\right\rangle=B_{\alpha \beta_{i}}  \tag{34}\\
& \text { and } \quad \lim _{x_{\alpha \beta_{i}} \rightarrow l_{\alpha \beta_{i}}}\left\langle\tau\left(x_{\alpha \beta_{i}}\right)\right\rangle \equiv\left\langle\tau_{\beta_{i}}\right\rangle=K_{\left(\alpha \beta_{i}\right)}+A_{\alpha \beta_{i}} J_{\left(\alpha \beta_{i}\right)}+B_{\alpha \beta_{i}}, \tag{35}
\end{align*}
$$

where

$$
\begin{align*}
K_{(\alpha \beta)} & =\int_{0}^{l_{\alpha \beta}} \mathrm{d} u_{\alpha \beta} \phi\left(u_{\alpha \beta}\right),  \tag{36}\\
J_{(\alpha \beta)} & =\int_{0}^{l_{\alpha \beta}} \mathrm{d} u_{\alpha \beta} I\left(u_{\alpha \beta}\right) . \tag{37}
\end{align*}
$$

In general, $K_{(\alpha \beta)} \neq K_{(\beta \alpha)}, J_{(\alpha \beta)} \neq J_{(\beta \alpha)}$.
Of course, $\left\langle\tau_{\lambda}\right\rangle=0$ if $\lambda$ is absorbing. So, we will determine $\left\langle\tau_{\alpha}\right\rangle$ only for $\alpha$ non-absorbing. In such a vertex, the current conservation leads to (14)-(16):

$$
\begin{equation*}
\sum_{i} p_{\alpha \beta_{i}}^{\prime} A_{\alpha \beta_{i}}=0 . \tag{38}
\end{equation*}
$$

Equations for the $\left\langle\tau_{\alpha}\right\rangle$ 's can be written in a matrix form, and finally, the average time spent on $\mathcal{D}$, before absorption, by a particle starting from $\alpha$ is given by

$$
\begin{equation*}
\left\langle\tau_{\alpha}\right\rangle=\frac{\operatorname{det} M_{1}}{\operatorname{det} M}, \tag{39}
\end{equation*}
$$

where $M$ and $M_{1}$ are two $(V-N) \times(V-N)$ matrices with the elements

$$
\begin{align*}
M_{i i} & =\sum_{m} \frac{p_{i m}^{\prime}}{J_{(i m)}}  \tag{40}\\
M_{i j} & =-\frac{p_{i j}^{\prime}}{J_{(i j)}} \tag{41}
\end{align*}
$$



Figure 2. Three simple graphs that are used to compute survival times (parts (a) and (b)) or covering time (c). In (a) and (b), the vertex 1 is absorbing. The Brownian particle starts from 0 (parts $(a)$ and $(c))$ and from $\lambda$ (part $(b)$. For further explanations, see the text.


Figure 3. The potential is symmetric around 0 except for a step of magnitude $\Delta U$.
(In (40) and (41), $i$ and $j$ run only over non-absorbing vertices but $m$ labels all kinds of vertices.) $M_{1}=M$ except for the $\alpha$ th column

$$
\begin{equation*}
\left(M_{1}\right)_{i \alpha}=-\sum_{m} p_{i m}^{\prime} \frac{K_{(i m)}}{J_{(i m)}} . \tag{42}
\end{equation*}
$$

We observe that, for a graph without any absorbing vertex, we have $\sum_{j} M_{i j}=0 \forall i$. Thus, $\operatorname{det} M$ vanishes and $\left\langle\tau_{\alpha}\right\rangle$ becomes infinite as expected.

Remark also that, when $\mathcal{D}=\mathcal{G}, \tau$ becomes the survival time or, accordingly, the firstpassage time in any absorbing vertex.

### 4.1.1. Examples.

Example 1. As a first example, let us consider the case $\mathcal{D}=\mathcal{G}$ for the graphs of figure 2:
In (a), the vertex 1 is absorbing and the particle starts from 0 . We get

$$
\begin{equation*}
\left\langle\tau_{0}\right\rangle=-K_{(01)} . \tag{43}
\end{equation*}
$$

In (b), 1 is still absorbing and the particle starts from $\lambda$. Its probability transition in 0 is $p_{01}=q\left(p_{0 \lambda}=1-q\right)$. Moreover, we assume that $l_{01}=l_{0 \lambda}, U\left(x_{01}\right)=U\left(x_{0 \lambda}\right)+\Delta U$ (a step of magnitude $\Delta U$ occurs in 0 , see figure 3 ) and $D\left(x_{01}\right)=D\left(x_{0 \lambda}\right)$. The mean survival time is given by

$$
\begin{equation*}
\left\langle\tau_{\lambda}(q)\right\rangle=-\left(\frac{K_{(01)}+K_{(10)}}{q}\right)\left(q+(1-q) \mathrm{e}^{\frac{\Delta U}{D(0)}}\right) \tag{44}
\end{equation*}
$$



Figure 4. The graph $\mathcal{G}$ consists in five vertices (3 and 4: absorbing, 0 : starting point), $U(x)$ is discontinuous in 1 and 2, and $D(x)$ is discontinuous in 0 .
(c) represents a symmetric star with $n$ legs of length $l$ originating from 0 ( $p_{0 i}=\frac{1}{n}$ and $U\left(x_{0 i}\right)=U\left(x_{0 j}\right)$ (no step in 0 this time), $D\left(x_{0 i}\right)=D\left(x_{0 j}\right) \forall i, j=1, \ldots, n$ ). Let us compute the average covering time $\left\langle\tau_{c}\right\rangle$ (smallest time necessary to reach all the points of the star at least once). With the notations of (43) and (44), we get, with $\Delta U=0$,

$$
\begin{align*}
\left\langle\tau_{c}\right\rangle & =\left\langle\tau_{0}\right\rangle+\sum_{k=1}^{n-1}\left\langle\tau_{\lambda}(1-k / n)\right\rangle  \tag{45}\\
& =-K_{(01)}-\left(K_{(01)}+K_{(10)}\right) n \sum_{k=1}^{n-1} \frac{1}{k}  \tag{46}\\
& \sim-\left(K_{(01)}+K_{(10)}\right) n \ln n \quad \text { when } \quad n \rightarrow \infty . \tag{47}
\end{align*}
$$

(Recall that for random walks on a star, $\left\langle\tau_{c}\right\rangle \sim 2 n \ln n$ [23].)
Example 2. Let us consider the graph of figure 4. Among the five vertices, two are absorbing (3 and 4). The starting point is $0 . U(x)$ is discontinuous in vertices 1 and $2 ; D(x)$ is discontinuous in vertex 0 . All the links have the same length $l$. With the backward equation, we get the mean survival time (39)
$\left\langle\tau_{0}\right\rangle=l^{2}\left(\frac{p_{01}}{D_{1}}+\frac{p_{02}}{D_{2}}\right) /\left(\frac{p_{01} p_{13}}{p_{13}+p_{10} \mathrm{e}^{\left(U_{1}-U\right) / D_{1}}}+\frac{p_{02} p_{24}}{p_{24}+p_{20} \mathrm{e}^{\left(U_{2}-U\right) / D_{2}}}\right)$.
Let us now compute $\left\langle\tau_{0}\right\rangle$ with the forward equation. Defining $\mathcal{P}(y) \equiv \int_{0}^{\infty} \mathrm{d} t P(y t \mid 00)$, we have
on the link [31]: $\quad \mathcal{P}\left(y_{31}\right)=a_{1} y_{31}+a_{2}$
on the link [10]: $\quad \mathcal{P}\left(y_{01}\right)=b_{1} y_{01}+b_{2}$
on the link [02]: $\quad \mathcal{P}\left(y_{02}\right)=c_{1} y_{02}+c_{2}$
on the link [24]: $\quad \mathcal{P}\left(y_{42}\right)=d_{1} y_{42}+d_{2}$,




Figure 5. The graph $\mathcal{G}$ consists in three vertices (2: absorbing, 0: starting point, pure reflection in 1 ); the drift $U(x)$ is linear, and $D(x)$ is discontinuous in 0 .
with the boundary conditions
$\mathcal{P}_{(31)}=0 \quad \mathcal{P}_{(42)}=0 \quad \frac{D_{1} \mathcal{P}_{(01)}}{p_{01}}=\frac{D_{2} \mathcal{P}_{(02)}}{p_{02}}$
$\frac{\mathrm{e}^{U_{1} / D_{1}} \mathcal{P}_{(13)}}{p_{13}}=\frac{\mathrm{e}^{U / D_{1}} \mathcal{P}_{(10)}}{p_{10}} \quad \frac{\mathrm{e}^{U_{2} / D_{2}} \mathcal{P}_{(24)}}{p_{24}}=\frac{\mathrm{e}^{U / D_{2}} \mathcal{P}_{(20)}}{p_{20} l}$
$\mathcal{P}_{(13)}^{\prime}+\mathcal{P}_{(10)}^{\prime}=0 \quad \mathcal{P}_{(24)}^{\prime}+\mathcal{P}_{(20)}^{\prime}=0 \quad D_{2} \mathcal{P}_{(02)}^{\prime}+D_{1} \mathcal{P}_{(01)}^{\prime}=-1$.
Solving those conditions and computing $\left\langle\tau_{0}\right\rangle=\int_{\mathcal{G}} \mathcal{P}(y) \mathrm{d} y=\left(b_{2}+c_{2}\right) l$, we recover the result equation (48).

Example 3. For the graph of figure 5, the starting point is 0 , a pure reflection occurs in 1 $\left(p_{10}=1\right)$, and the vertex 2 is absorbing. The potential is $U\left(x_{02}\right)=a x_{02}, U\left(x_{01}\right)=-a x_{01}$. With the notations of the figure and using the backward result (39), we get the mean residence time:

$$
\begin{array}{ll}
\text { on the link [10] : } & \left\langle\tau_{0}\right\rangle=\frac{p_{01}}{p_{02}} \frac{D_{2}}{a^{2}}\left(\mathrm{e}^{a l_{2} / D_{2}}-1\right)\left(\mathrm{e}^{a l_{1} / D_{1}}-1\right) \\
\text { on the link [02]: } & \left\langle\tau_{0}\right\rangle=\frac{D_{2}}{a^{2}}\left(\mathrm{e}^{a l_{2} / D_{2}}-1-\frac{a l_{2}}{D_{2}}\right) . \tag{57}
\end{array}
$$

Taking the limit $a \rightarrow 0$ (no drift), we obtain

$$
\begin{array}{ll}
\text { on the link [10] : } & \left\langle\tau_{0}\right\rangle=\frac{p_{01}}{p_{02}} \frac{l_{1} l_{2}}{D_{1}} \\
\text { on the link [02] : } & \left\langle\tau_{0}\right\rangle=\frac{l_{2}^{2}}{2 D_{2}} . \tag{59}
\end{array}
$$

Turning to the forward equation, still with $\mathcal{P}(y) \equiv \int_{0}^{\infty} \mathrm{d} t P(y t \mid 00)$, we have

$$
\begin{array}{ll}
\text { on the link [10]: } & \mathcal{P}\left(y_{01}\right)=c_{1} \mathrm{e}^{a y_{01} / D_{1}}+c_{2} \\
\text { on the link [02]: } & \mathcal{P}\left(y_{02}\right)=c_{3} \mathrm{e}^{-a y_{02} / D_{2}}+c_{4} \tag{61}
\end{array}
$$

with the conditions

$$
\begin{align*}
& \mathcal{P}_{(20)}=0 \quad \frac{D_{1} \mathcal{P}_{(01)}}{p_{01}}=\frac{D_{2} \mathcal{P}_{(02)}}{p_{02}} \quad D_{1} \mathcal{P}_{(10)}^{\prime}+a \mathcal{P}_{(10)}=0  \tag{62}\\
& D_{2} \mathcal{P}_{(02)}^{\prime}+D_{1} \mathcal{P}_{(01)}^{\prime}+a\left(\mathcal{P}_{(02)}-\mathcal{P}_{(01)}\right)=-1 \tag{63}
\end{align*}
$$

Computing $\left\langle\tau_{0}\right\rangle=\int_{\mathcal{D}} \mathcal{P}(y) \mathrm{d} y=c_{1} \frac{D_{1}}{a}\left(\mathrm{e}^{a l_{1} / D_{1}}-1\right)+c_{2} l_{1}$ for the link [10], $=c_{3} \frac{D_{2}}{a}(1-$ $\left.\mathrm{e}^{-a l_{2} / D_{2}}\right)+c_{4} l_{2}$ for the link [02], we recover solutions (56) and (57).

### 4.2. Occupation times distribution

Still with the same conditions (drift, spatially dependent diffusion constant, absorbing vertices, ...), we now study a Brownian motion stopped at $t$ and call $T_{\alpha \beta}$ the time spent up to $t$ on the link $[\alpha \beta]$.
$T_{\alpha \beta}$ is, of course, a random variable depending on $t$, and we will call $\mathcal{P}_{t}\left(\left\{T_{\alpha \beta}\right\}\right)$ the joint distribution of the $T_{\alpha \beta}$ 's.

In the following, we will focus our attention on the quantity

$$
\begin{align*}
S(t \mid x 0) & =\int \prod_{[\alpha \beta]} \mathrm{d} T_{\alpha \beta} \mathcal{P}_{t}\left(\left\{T_{\alpha \beta}\right\}\right) \mathrm{e}^{-\sum_{[i j]} \xi_{i j} T_{i j}}  \tag{64}\\
& \equiv\left\langle\mathrm{e}^{-\sum_{[i j]} \xi_{i j} T_{i j}}(x)\right\rangle, \tag{65}
\end{align*}
$$

where the $\xi_{i j}$ 's are positive constants, and $\langle\ldots(x)\rangle$ stands for averaging over all the Brownian trajectories starting from $x$ and developing up to $t$ in the presence of the drift.

In order to stick to $S(t \mid x 0)$, we slightly modify the backward equation (1) by adding, on each link $[\alpha \beta]$, a loss term proportional to $\xi_{\alpha \beta}\left(\xi_{\alpha \beta}\right.$ may be interpreted as a reaction rate per unit length and time). Thus, we consider the equation

$$
\begin{equation*}
\frac{\partial Q}{\partial t}=\left(L^{+}\left(x_{\alpha \beta}\right)-\xi_{\alpha \beta}\right) Q \tag{66}
\end{equation*}
$$

where $Q(y t \mid x 0)$ represents the probability of finding the particle in $y$ at time $t$, each path from $x$ to $y$ being, this time, weighted by a factor $\mathrm{e}^{-\sum_{\{\alpha \beta\}} \xi_{\alpha \beta} T_{\alpha \beta}}$. (Note that $Q(y t \mid x 0)=\delta(y-x)$ if $x$ is absorbing.)

It is now easy to realize that we have the relationship

$$
\begin{equation*}
S(t \mid x 0)=\int_{\mathcal{G}} \mathrm{d} y Q(y t \mid x 0) \tag{67}
\end{equation*}
$$

In the following, we will be especially interested in the Laplace transform of $S(t \mid x 0)$ :

$$
\begin{equation*}
\widehat{S}(\gamma \mid x 0) \equiv \widehat{S}(x)=\int_{0}^{\infty} \mathrm{d} t \mathrm{e}^{-\gamma t} S(t \mid x 0) \tag{68}
\end{equation*}
$$

On the bond $[\alpha \beta], \widehat{S}\left(x_{\alpha \beta}\right)$ satisfies the following equation $\left(\gamma_{\alpha \beta} \equiv \gamma+\xi_{\alpha \beta}\right)$ :

$$
\begin{equation*}
\left(L^{+}\left(x_{\alpha \beta}\right)-\gamma_{\alpha \beta}\right) \widehat{S}=-1 . \tag{69}
\end{equation*}
$$

Setting $\widehat{S}\left(x_{\alpha \beta}\right)=\frac{1}{\gamma_{\alpha \beta}}+\Phi\left(x_{\alpha \beta}\right)$ and performing the transformation

$$
\begin{equation*}
\Phi\left(x_{\alpha \beta}\right)=\sqrt{I\left(x_{\alpha \beta}\right)} \chi\left(x_{\alpha \beta}\right) \tag{70}
\end{equation*}
$$

( $I$ is defined in (33)), we are left with the following equation for $\chi$ :
$-D \frac{\partial^{2} \chi}{\partial x_{\alpha \beta}^{2}}+\left[\frac{1}{4 D}\left(\frac{\partial U\left(x_{\alpha \beta}\right)}{\partial x_{\alpha \beta}}\right)^{2}-D \frac{\partial}{\partial x_{\alpha \beta}}\left(\frac{1}{2 D} \frac{\partial U\left(x_{\alpha \beta}\right)}{\partial x_{\alpha \beta}}\right)+\gamma_{\alpha \beta}\right] \chi=0$.
Let us call $\chi_{\alpha \beta}$ and $\chi_{\beta \alpha}$ two solutions of (71) such that $\chi_{\alpha \beta}(\alpha)=\chi_{\beta \alpha}(\beta)=1, \chi_{\beta \alpha}(\alpha)=$ $\chi_{\alpha \beta}(\beta)=0$. So,,$S$ writes

$$
\begin{align*}
\widehat{S}=\frac{1}{\gamma_{\alpha \beta}}+A_{\alpha \beta} & \exp \left(\int_{0}^{x_{\alpha \beta}} \frac{\mathrm{d} z_{\alpha \beta}}{2 D\left(z_{\alpha \beta}\right)} \frac{\partial U\left(z_{\alpha \beta}\right)}{\partial z_{\alpha \beta}}\right) \chi_{\alpha \beta}\left(x_{\alpha \beta}\right) \\
& +A_{\beta \alpha} \exp \left(\int_{l_{\alpha \beta}}^{x_{\alpha \beta}} \frac{\mathrm{d} z_{\alpha \beta}}{2 D\left(z_{\alpha \beta}\right)} \frac{\partial U\left(z_{\alpha \beta}\right)}{\partial z_{\alpha \beta}}\right) \chi_{\beta \alpha}\left(x_{\alpha \beta}\right) . \tag{72}
\end{align*}
$$

The constants $A_{i j}$ are determined by imposing the boundary conditions. Continuity of $\widehat{S}$ at each vertex $\alpha$ implies

$$
\begin{equation*}
\lim _{x_{\alpha \beta_{i}} \rightarrow 0} \widehat{S}\left(x_{\alpha \beta_{i}}\right) \equiv \widehat{S}_{\alpha}=\frac{1}{\gamma_{\alpha \beta_{i}}}+A_{\alpha \beta_{i}} \tag{73}
\end{equation*}
$$

Moreover, if $\alpha$ is absorbing then $T_{\lambda \mu}=0 \forall[\lambda \mu]$ and, from (64) and (68), we get

$$
\begin{equation*}
\widehat{S}_{\alpha}=\frac{1}{\gamma}=\frac{1}{\gamma_{\alpha \beta_{i}}}+A_{\alpha \beta_{i}} \tag{74}
\end{equation*}
$$

Following the same lines as for $\left\langle\tau_{\alpha}\right\rangle$, it is easy to show that the $\widehat{S}_{\alpha}$ 's ( $\alpha$ non-absorbing) satisfy a matrix equation with the solution

$$
\begin{equation*}
\widehat{S}_{\alpha}=\frac{\operatorname{det} R_{1}}{\operatorname{det} R} \tag{75}
\end{equation*}
$$

where $R$ and $R_{1}$ are again $(V-N) \times(V-N)$ matrices with elements

$$
\begin{align*}
R_{i i} & =\sum_{m} p_{i m}^{\prime} C_{i m}  \tag{76}\\
R_{i j} & =p_{i j}^{\prime} W_{i j} \tag{77}
\end{align*}
$$

the quantities $C_{i m}$ and $W_{i j}$ being given by

$$
\begin{align*}
C_{i m} & =\lim _{x_{i m} \rightarrow 0}\left(\frac{\partial \chi_{i m}}{\partial x_{i m}}+\frac{\frac{\partial U}{\partial x_{i m}}}{2 D\left(x_{i m}\right)}\right),  \tag{78}\\
W_{i j} & =\exp \left(\int_{l_{i j}}^{0} \frac{\frac{\partial U}{\partial x_{i j}}}{2 D\left(x_{i j}\right)} \mathrm{d} x_{i j}\right) \lim _{x_{i j} \rightarrow 0} \frac{\partial \chi_{j i}}{\partial x_{i j}} . \tag{79}
\end{align*}
$$

$R_{1}=R$ except for the $\alpha$ th column

$$
\begin{equation*}
\left(R_{1}\right)_{i \alpha}=\sum_{j} \frac{p_{i j}^{\prime}}{\gamma_{i j}}\left(C_{i j}+W_{i j}\right)-\frac{1}{\gamma} \sum_{k \mathrm{abs} .} p_{i k}^{\prime} W_{i k} \tag{80}
\end{equation*}
$$

(The last summation is performed only over absorbing vertices.)

Setting $\xi_{i j} \equiv 0$, we establish that $\operatorname{det} R_{1}=\frac{1}{\gamma} \operatorname{det} R$, showing that the probability distribution $\mathcal{P}_{t}\left(\left\{T_{\alpha \beta}\right\}\right)$ is properly normalized (see (64) and (68)).

Now, let us call $T_{\alpha \beta}^{\prime}$ the time spent on $[\alpha \beta]$ before absorption. Thus, for a particle starting from $\alpha$, we can write

$$
\begin{equation*}
\left\langle\mathrm{e}^{-\sum_{[i j} \xi_{i j} T_{i j}^{\prime}}(\alpha)\right\rangle=\lim _{t \rightarrow \infty}\left\langle\mathrm{e}^{-\sum_{[i j]} \xi_{i j} T_{i j}}(\alpha)\right\rangle \tag{81}
\end{equation*}
$$

and from (65) and (68) we deduce

$$
\begin{equation*}
\left\langle\mathrm{e}^{-\sum_{i j j} \xi_{i j} T_{i j}^{\prime}}(\alpha)\right\rangle=\lim _{\gamma \rightarrow 0}\left(\gamma \widehat{S}_{\alpha}\right) \tag{82}
\end{equation*}
$$

Finally, we get

$$
\begin{equation*}
\left\langle\mathrm{e}^{-\sum_{[i j]} \xi_{i j} T_{i j}^{\prime}}(\alpha)\right\rangle=\frac{\operatorname{det} R_{1}^{(0)}}{\operatorname{det} R^{(0)}} \tag{83}
\end{equation*}
$$

with $R^{(0)}=\lim _{\gamma \rightarrow 0} R$ and $R_{1}^{(0)}=R^{(0)}$ except for the $\alpha$ th column that is given by

$$
\begin{equation*}
\left(R_{1}^{(0)}\right)_{i \alpha}=-\lim _{\gamma \rightarrow 0} \sum_{k \text { abs. }} p_{i k}^{\prime} W_{i k} \tag{84}
\end{equation*}
$$

(84) holds because

$$
\lim _{\gamma \rightarrow 0}\left(\frac{\gamma}{\gamma_{i j}} p_{i j}^{\prime}\left(C_{i j}+W_{i j}\right)\right)=0
$$

This is obvious when $\xi_{i j} \neq 0$. But when $\xi_{i j}=0$, this is still true because, in that case, $\lim _{\gamma \rightarrow 0}\left(C_{i j}+W_{i j}\right)=0$.

Remark that (84) implies that $\left\langle\mathrm{e}^{-\sum_{i j j} \xi_{i j} T_{i j}^{\prime}}(\alpha)\right\rangle=0$ if $\mathcal{G}$ has no absorbing vertex (in that case, $T_{i j}^{\prime}=\infty$ ).

Setting $\xi_{i j} \equiv \xi$ and $\sum_{[i j]} T_{i j}^{\prime} \equiv \tau$ (survival time), (83) gives the expression of the Laplace transform of the probability distribution of $\tau$.
4.2.1. Example. To illustrate this work, let us go back to the example of figure 2 and study the survival time (parts $(a)$ and $(b)$-with $\Delta U=0$ ) and covering time (part $(c)$ ) distributions.

With (a), we get

$$
\begin{equation*}
\left\langle\mathrm{e}^{-\xi \tau_{0}}\right\rangle=-\frac{W_{01}}{C_{01}} \tag{85}
\end{equation*}
$$

$\left(W_{\alpha \beta}, C_{\alpha \beta}, \ldots\right.$ are computed with $\gamma_{\alpha \beta}=\xi$ ).
(b) leads to

$$
\begin{equation*}
\left\langle\mathrm{e}^{-\xi \tau_{\lambda}}(q)\right\rangle=-\frac{q}{Z-1+q} \tag{86}
\end{equation*}
$$

with $Z=\frac{C_{01} C_{10}}{W_{01} W_{10}}$.
For the covering time $\tau_{c}$ in (c) we get (with the notations of (43) and (44))

$$
\begin{align*}
\left\langle\mathrm{e}^{-\xi \tau_{c}}\right\rangle & =-\left\langle\mathrm{e}^{-\xi \tau_{0}}\right\rangle \prod_{k=1}^{n-1}\left\langle\mathrm{e}^{-\xi \tau_{\lambda}}(1-k / n)\right\rangle  \tag{87}\\
& =-\frac{W_{01}}{C_{01}} \frac{(n-1)!}{n^{n-1}} \prod_{k=1}^{n-1} \frac{1}{Z-\frac{k}{n}} . \tag{88}
\end{align*}
$$

Computation of the first moments shows that, when $n \rightarrow \infty$,

$$
\begin{align*}
& \left\langle\tau_{c}\right\rangle \propto n \ln n \text { in agreement with (47) }  \tag{89}\\
& \left\langle\tau_{c}^{2}\right\rangle-\left\langle\tau_{c}\right\rangle^{2} \propto n^{2} . \tag{90}
\end{align*}
$$

Then the probability distribution of the scaling variable $\tau_{c} /\left\langle\tau_{c}\right\rangle$ becomes more and more peaked at its mean value when $n \rightarrow \infty$ :

$$
\begin{equation*}
P\left(\frac{\tau_{c}}{\left\langle\tau_{c}\right\rangle}=X\right) \rightarrow_{n \rightarrow \infty} \delta(X-1) \tag{91}
\end{equation*}
$$

## 5. First-passage times

This section is essentially devoted to a detailed study of exit (or survival) times. First, we will compute exit times distributions and, after in the last parts, we will focus on quantities concerning exit through a given absorbing vertex.

### 5.1. Exit times distribution

The density of exit time $\mathcal{P}(t \mid x 0)$ (without specifying the absorbing vertex) is defined through the loss of probability:

$$
\begin{align*}
& \mathcal{P}(t \mid x 0) \mathrm{d} t=\int_{\mathcal{G}} \mathrm{d} y P(y t \mid x 0)-\int_{\mathcal{G}} \mathrm{d} y P(y, t+\mathrm{d} t \mid x 0)  \tag{92}\\
& \text { Thus : } \quad \mathcal{P}(t \mid x 0)=-\frac{\partial}{\partial t} \int_{\mathcal{G}} \mathrm{d} y P(y t \mid x 0) \equiv \sum_{\mu \text { abs. }} \mathcal{P}_{\mu}(t \mid x 0) \tag{93}
\end{align*}
$$

where $\mathcal{P}_{\mu}(t \mid x 0)$ is the density of exit time by the absorbing vertex $\mu$.
With the forward Fokker-Planck equation, (93) leads to

$$
\begin{align*}
& \mathcal{P}(t \mid x 0)=-\int_{\mathcal{G}} \mathrm{d} y L(y) P(y t \mid x 0)=\sum_{\mu \text { abs. }, i} J_{\mu \beta_{i}}  \tag{94}\\
& J_{\mu \beta_{i}}=\lim _{y_{\mu \beta_{i}} \rightarrow 0}\left(\frac{\partial}{\partial y_{\mu \beta_{i}}}(D P)+\frac{\partial U}{\partial y_{\mu \beta_{i}}} P\right)  \tag{95}\\
& \quad=\lim _{y_{\mu \beta_{i} \rightarrow 0}}\left(D \frac{\partial P}{\partial y_{\mu \beta_{i}}}\right), \tag{96}
\end{align*}
$$

because $P_{\left(\mu \beta_{i}\right)}=0$ when $\mu$ is absorbing. (The $\beta_{i}$ 's are the nearest neighbours of $\mu$ on $\mathcal{G}$.)
We deduce that $\mathcal{P}_{\mu}(t \mid x 0)$ is the probability current at vertex $\mu: \mathcal{P}_{\mu}(t \mid x 0)=\sum_{i} J_{\mu \beta_{i}}$.
Let us compute the Laplace transform, $\widehat{\mathcal{P}}(\gamma \mid x 0)$, of $\mathcal{P}(t \mid x 0)$. With (93), we get

$$
\begin{align*}
\widehat{\mathcal{P}}(\gamma \mid x 0) & =\int_{0}^{\infty} \mathrm{d} t \mathrm{e}^{-\gamma t}\left(-\frac{\partial}{\partial t} \int_{\mathcal{G}} \mathrm{d} y P(y t \mid x 0)\right) \equiv \sum_{\mu \text { abs. }} \widehat{\mathcal{P}}_{\mu}(\gamma \mid x 0)  \tag{97}\\
& =1-\gamma \int_{0}^{\infty} \mathrm{d} t \mathrm{e}^{-\gamma t} \int_{\mathcal{G}} \mathrm{d} y P(y t \mid x 0) \tag{98}
\end{align*}
$$

The backward Fokker-Planck equation gives

$$
\begin{align*}
& L^{+} \widehat{\mathcal{P}}(\gamma \mid x 0)=\gamma \widehat{\mathcal{P}}(\gamma \mid x 0)  \tag{99}\\
& \text { and } \quad L^{+} \widehat{\mathcal{P}_{\mu}}(\gamma \mid x 0)=\gamma \widehat{\mathcal{P}}_{\mu}(\gamma \mid x 0) . \tag{100}
\end{align*}
$$

Defining $\widehat{\mathcal{P}}_{\mu, \alpha}=\lim _{x_{\alpha i} \rightarrow 0} \widehat{\mathcal{P}}_{\mu}\left(\gamma \mid x_{\alpha i} 0\right)$, we remark that

$$
\begin{align*}
& \text { for an absorbing vertex } \lambda: \quad \widehat{\mathcal{P}}_{\mu, \lambda}=\delta_{\mu \lambda} .  \tag{101}\\
& \text { This is because } \quad \begin{aligned}
\mathcal{P}_{\mu}(t \mid \lambda 0) & =\delta(t) \quad \text { if } \lambda=\mu \\
& =0 \quad \text { otherwise. }
\end{aligned} \tag{102}
\end{align*}
$$

Following section 4.2, we readily find, for a particle starting from $\alpha$ (non-absorbing), the Laplace transform of the exit (by the vertex $\mu$ ) time distribution:

$$
\begin{equation*}
\widehat{\mathcal{P}}_{\mu, \alpha}=\frac{\operatorname{det} R_{2}^{(\mu, \alpha)}}{\operatorname{det} R} \tag{104}
\end{equation*}
$$

where $R_{2}^{(\mu, \alpha)}=R$ except for the $\alpha$ th column

$$
\begin{equation*}
\left(R_{2}^{(\mu, \alpha)}\right)_{i \alpha}=-p_{i \mu}^{\prime} W_{i \mu} . \tag{105}
\end{equation*}
$$

$R$ and $W_{i \mu}$ are defined in (76)-(79) and computed here, with $\xi_{\alpha \beta} \equiv 0\left(p_{i \mu}^{\prime}\right.$ is defined in (15)-(16)).

### 5.2. Splitting probabilities

For a particle starting at $x$, we define the splitting probability $\Pi_{\mu}(x)$ as the probability of ever reaching the absorbing vertex $\mu$ (rather than any other absorbing vertex). Such a quantity has already been considered for one-dimensional systems [24] (see also [25] for extensions to higher-dimensional systems).

We have, obviously,

$$
\begin{equation*}
\Pi_{\mu}(x)=\int_{0}^{\infty} \mathrm{d} t \mathcal{P}_{\mu}(t \mid x 0)=\widehat{\mathcal{P}}_{\mu}(\gamma=0 \mid x 0) \tag{106}
\end{equation*}
$$

Setting $\gamma=0$ in (100) we see that $\Pi_{\mu}(x)$ satisfies, on $[\alpha \beta]$, the backward equation

$$
\begin{equation*}
L^{+}\left(x_{\alpha \beta}\right) \Pi_{\mu}\left(x_{\alpha \beta}\right)=0 \tag{107}
\end{equation*}
$$

The probability, $\Pi_{\mu, \alpha}$, for a particle starting from the vertex $\alpha$ to be absorbed by $\mu$, is defined as $\Pi_{\mu, \alpha}=\lim _{x_{\alpha i} \rightarrow 0} \Pi_{\mu}\left(x_{\alpha i}\right)$.

With (106) and (101), it is easy to realize that,

$$
\begin{equation*}
\text { for an absorbing vertex } \lambda, \quad \Pi_{\mu, \lambda}=\delta_{\mu \lambda} . \tag{108}
\end{equation*}
$$

Following the same lines as previously (see section 4.1), we find that $\Pi_{\mu, \alpha}$ ( $\alpha$ nonabsorbing) is again written as the ratio of two determinants:

$$
\begin{equation*}
\Pi_{\mu, \alpha}=\frac{\operatorname{det} M_{2}^{(\mu, \alpha)}}{\operatorname{det} M} \tag{109}
\end{equation*}
$$

where $M_{2}^{(\mu, \alpha)}=M$ except for the $\alpha$ th column

$$
\begin{equation*}
\left(M_{2}^{(\mu, \alpha)}\right)_{i \alpha}=\frac{p_{i \mu}^{\prime}}{J_{(i \mu)}} \tag{110}
\end{equation*}
$$

( $M$ is defined in (40) and (41) and $J_{(i \mu)}$ in (37)).

With simple manipulations on determinants, we check the normalization condition $\sum_{i \text { abs. }} \Pi_{i, \alpha}=1$.

Let us, for one moment, comment on the case when there is no drift $(U(x)$ constant but $D(x)$ variable, eventually discontinuous at some vertices). In that case $p_{i j}^{\prime}=p_{i j}$ and, also, $J_{(i j)}=l_{i j}$. We conclude that the splitting probabilities do not depend on the varying diffusion constant when there is no drift. This fact can be understood in the following way. Let us consider a discretization of each link and a continuous time. Modifying the diffusion constant amounts to change the waiting time at each site of the discretized graph. But, this would not change the trajectories if there is no drift. Only the time spent is changed. Finally, the splitting probabilities remain unaffected ${ }^{4}$ by a change of $D(x)$.
5.2.1. Example. Let us consider a star graph without drift. The root 0 has $m_{0}$ neighbours, all absorbing. The $m_{0}$ links have lengths $l_{0 i}, i=1, \ldots, m_{0}$. With (109), we obtain

$$
\begin{equation*}
\Pi_{i, 0}=\left(\frac{p_{0 i}}{l_{0 i}}\right) /\left(\sum_{m=1}^{m_{0}} \frac{p_{0 m}}{l_{0 m}}\right) \tag{111}
\end{equation*}
$$

### 5.3. Conditional mean first-passage times

We now turn to the study of the conditional mean first-passage time $\left\langle t_{\mu}(x)\right\rangle$, which is defined as the mean exit time, given that exit is through the absorbing vertex $\mu$ (rather than any other absorbing vertex). We set $\left\langle t_{\mu, \alpha}\right\rangle=\lim _{x_{\alpha i} \rightarrow 0}\left\langle t_{\mu}\left(x_{\alpha i}\right)\right\rangle$.

Actually, it is simpler to first compute the quantity $\theta_{\mu}(x) \equiv \Pi_{\mu}(x)\left\langle t_{\mu}(x)\right\rangle$.
Indeed, we have

$$
\begin{align*}
& \theta_{\mu}(x)=\int_{0}^{\infty} \mathrm{d} t t \mathcal{P}_{\mu}(t \mid x 0)  \tag{112}\\
& L^{+} \theta_{\mu}(x)=\int_{0}^{\infty} \mathrm{d} t t \frac{\partial}{\partial t} \mathcal{P}_{\mu}(t \mid x 0)=-\int_{0}^{\infty} \mathrm{d} t \mathcal{P}_{\mu}(t \mid x 0) \tag{113}
\end{align*}
$$

So, we get $L^{+} \theta_{\mu}(x)=-\Pi_{\mu}(x)$.
Moreover, for any absorbing vertex $\lambda$, we get $\theta_{\mu, \lambda}=\Pi_{\mu, \lambda}\left\langle t_{\mu, \lambda}\right\rangle=\delta_{\mu, \lambda}\left\langle t_{\mu, \mu}\right\rangle=0$ because $\left\langle t_{\mu, \mu}\right\rangle=0$.

Thus, comparing this equation with equation (30), we find, for a particle starting from the vertex $\alpha$,

$$
\begin{equation*}
\Pi_{\mu, \alpha}\left\langle t_{\mu, \alpha}\right\rangle=\frac{\operatorname{det} M_{3}^{(\mu, \alpha)}}{\operatorname{det} M} \tag{115}
\end{equation*}
$$

where $M_{3}^{(\mu, \alpha)}=M$ except for the $\alpha$ th column:

$$
\begin{equation*}
\left(M_{3}^{(\mu, \alpha)}\right)_{i \alpha}=\sum_{m} p_{i m}^{\prime} \frac{\widetilde{K}_{(i m)}^{(\mu)}}{J_{(i m)}} \tag{116}
\end{equation*}
$$

with

$$
\begin{equation*}
\widetilde{K}_{(i j)}^{(\mu)}=\int_{0}^{l_{i j}} \mathrm{~d} u_{i j} I\left(u_{i j}\right)\left(\int_{0}^{u_{i j}} \mathrm{~d} z_{i j} \frac{\Pi_{\mu}\left(z_{i j}\right)}{D\left(z_{i j}\right) I\left(z_{i j}\right)}\right) \tag{117}
\end{equation*}
$$

[^1]In this last equation, $\Pi_{\mu}\left(z_{i j}\right)$ has to be computed by the equation

$$
\begin{equation*}
\Pi_{\mu}\left(z_{i j}\right)=\Pi_{\mu, i}+\frac{\Pi_{\mu, j}-\Pi_{\mu, i}}{J_{(i j)}} \int_{0}^{z_{i j}} \mathrm{~d} u_{i j} I\left(u_{i j}\right) \tag{118}
\end{equation*}
$$

with $\Pi_{\mu, i}$ given by equation (109).
5.3.1. Example. With the same star graph as in section 5.2 .1 (no drift) and a diffusion constant equal to $D_{0 i}$ on each link [0i], we get (111) and (115):

$$
\begin{equation*}
\left\langle t_{\mu, 0}\right\rangle=\frac{1}{6} \frac{l_{0 \mu}^{2}}{D_{0 \mu}}+\frac{1}{3}\left(\sum_{m=1}^{m_{0}} p_{0 m} \frac{l_{0 m}}{D_{0 m}}\right) /\left(\sum_{m=1}^{m_{0}} \frac{p_{0 m}}{l_{0 m}}\right) \tag{119}
\end{equation*}
$$

## 6. Summary

We have used the Fokker-Planck equation (mainly the backward one) to compute some quantities relevant for the study of a Brownian particle moving on a graph. This particle, moving with a varying diffusion constant, is also subjected to a drift.

Being aware that this point is somewhat controversial (see, for instance, [26]), we have discussed in great details the boundary conditions in vertices where either $U(x)$ or $D(x)$ is discontinuous. Two appendices support the study of those boundary conditions.

Those preliminaries allowed us to deal with various quantities such as the mean residence time, the occupation times probabilities, the splitting probabilities and the conditional mean first-passage time. In each case, we have established general formulae that can be used for all kinds of graphs.

Finally, we have checked, on several examples, the consistency of the boundary conditions that we have put forward.

## Appendix A. Backward equation: boundary conditions when $\boldsymbol{p}_{\mathbf{0 1}}=\boldsymbol{p}_{\mathbf{0 2}}$

For a direct computation of the boundary conditions, it is simpler to consider the Laplace transform:

$$
\begin{equation*}
\widehat{S}(\gamma \mid x 0)=\int_{0}^{\infty} \mathrm{d} t \mathrm{e}^{-\gamma t} \int_{\mathcal{G}} \mathrm{d} y P(y t \mid x 0) \tag{A.1}
\end{equation*}
$$

that satisfies the backward equation $(\widehat{S}(\gamma \mid x 0) \equiv \widehat{S}(x))$ :

$$
\begin{equation*}
\left(L^{+}-\gamma\right) \widehat{S}(x)=-1 \tag{A.2}
\end{equation*}
$$

First, we want to study the case (A).
For the simple graph of figure $\mathrm{A} 1(a), D(x)$ is continuous and $U(x)$ is discontinuous at the vertex 0 . In particular, $U_{(01)} \equiv U_{1} \neq U_{(02)} \equiv U_{2} ; D(0) \equiv D$. Moreover, vertices 1 and 2 are absorbing and, in 0 , the transition probabilities are equal: $p_{01}=p_{02}=1 / 2$.

Now, let us add to this graph, the link [03] of length $L$ (see figure A1(b)) in such a way that nothing is changed for the rest (for example, the potential on the link [02] of the original graph is the same as that on the link [32] of the modified graph, ...). On [03], we define $U\left(x_{03}\right)=\left(\frac{U_{2}-U_{1}}{L}\right) x_{03}+U_{1}$ and $D\left(x_{03}\right) \equiv D$. When $L \rightarrow 0$, we recover figure $\mathrm{A} 1(a)$.

Working with this modified graph, the solution of (A.2) writes
on the link [10]: $\quad \widehat{S}\left(x_{10}\right)=1 / \gamma+a_{1} \phi_{1}\left(x_{10}\right)+a_{2} \phi_{2}\left(x_{10}\right)$
on the link [03]: $\quad \widehat{S}\left(x_{03}\right)=1 / \gamma+c_{1} \mathrm{e}^{r_{+} x_{03}}+c_{2} \mathrm{e}^{r_{-} x_{03}}$


Figure A1. In part (a) a simple graph with the absorbing vertices 1 and 2; the potential is discontinuous in 0 . In part (b), we add the link [03] (length $L$ ) and, on this link, a potential that interpolates linearly between $U_{1}$ and $U_{2} ; D(x)$ is constant on [03].

$$
\begin{equation*}
\text { on the link [32]: } \quad \widehat{S}\left(x_{32}\right)=1 / \gamma+b_{1} \psi_{1}\left(x_{32}\right)+b_{2} \psi_{2}\left(x_{32}\right) \tag{A.5}
\end{equation*}
$$

with

$$
\begin{align*}
& r_{ \pm}=\frac{A \pm \sqrt{A^{2}+4 \gamma D}}{2 D}  \tag{A.6}\\
& A=\frac{U_{2}-U_{1}}{L} . \tag{A.7}
\end{align*}
$$

$\phi_{1,2}$ and $\psi_{1,2}$ are solutions of the equation $\left(L^{+}-\gamma\right) \phi=0$ that satisfy $\left(\phi_{(\alpha \beta)} \equiv\right.$ $\left.\lim _{x_{\alpha \beta} \rightarrow 0} \phi\left(x_{\alpha \beta}\right)\right):$

$$
\begin{array}{llll}
\phi_{1(10)}=0 & \phi_{1(01)}=1 & \phi_{2(10)}=1 & \phi_{2(01)}=0 \\
\psi_{1(32)}=1 & \psi_{1(23)}=0 & \psi_{2(32)}=0 & \psi_{2(23)}=1 \tag{A.9}
\end{array}
$$

$U(x)$ and $D(x)$ are continuous everywhere on the graph. So, we write standard boundary conditions at the vertices (continuity of $\widehat{S}$ and its derivative at vertices 0 and 3 ; $\widehat{S}=0$ at vertices 1 and 2). We obtain $\left(\phi_{(\alpha \beta)}^{\prime} \equiv \lim _{x_{\alpha \beta} \rightarrow 0} \frac{\partial \phi\left(x_{\alpha \beta}\right)}{\partial x_{\alpha \beta}}\right)$

$$
\begin{align*}
& a_{2}=b_{2}=-\frac{1}{\gamma} \quad a_{1}=c_{1}+c_{2} \quad b_{1}=c_{1} \mathrm{e}^{r_{+} L}+c_{2} \mathrm{e}^{r_{-} L}  \tag{A.10}\\
& a_{1} \phi_{1(01)}^{\prime}+a_{2} \phi_{2(01)}^{\prime}+c_{1} r_{+}+c_{2} r_{-}=0  \tag{A.11}\\
& b_{1} \psi_{1(32)}^{\prime}+b_{2} \psi_{2(32)}^{\prime}-c_{1} r_{+} \mathrm{e}^{r_{+} L}-c_{2} r_{-} \mathrm{e}^{r_{-} L}=0 . \tag{A.12}
\end{align*}
$$

After some algebra, we get the results

$$
\begin{equation*}
\frac{\widehat{S}_{(32)}}{\widehat{S}_{(01)}}=\frac{\frac{1}{\gamma}+b_{1}}{\frac{1}{\gamma}+a_{1}} \rightarrow_{L \rightarrow 0} 1 \tag{A.13}
\end{equation*}
$$



Figure A2. (a) The same graph as in figure $\mathrm{A} 1(a)$ but this time $D(x)$ is discontinuous in 0 ; in part (b), a parabolic interpolation is used to make $D(x)$ continuous; $U(x)$ is constant on the link [03].

$$
\begin{equation*}
\frac{\widehat{S}_{(32)}^{\prime}}{\widehat{S}_{(01)}^{\prime}}=\frac{b_{1} \psi_{1(32)}^{\prime}+b_{2} \psi_{2(32)}^{\prime}}{a_{1} \phi_{1(01)}^{\prime}+a_{2} \phi_{2(01)}^{\prime}} \rightarrow_{L \rightarrow 0}-\mathrm{e}^{\left(U_{2}-U_{1}\right) / D} \tag{A.14}
\end{equation*}
$$

When $L \rightarrow 0$, the vertex 3 moves to 0 and equations (A.13) and (A.14) give, for the original graph,

$$
\begin{align*}
& \widehat{S}_{(01)}=\widehat{S}_{(02)}  \tag{A.15}\\
& \widehat{S}_{(01)}^{\prime} \mathrm{e}^{-U_{(01)} / D(0)}+\widehat{S}_{(02)}^{\prime} \mathrm{e}^{-U_{(02)} / D(0)}=0 . \tag{A.16}
\end{align*}
$$

In particular, we observe that $\widehat{S}$ is continuous at 0 and that exponential factors appear in the condition involving the derivatives.

Let us now turn to the case (B), still with the same graph and $p_{01}=p_{02}=1 / 2$.
This time (figure A2(a)), $D(x)$ is discontinuous at 0 and $U(x)$ is continuous. We set $D_{(01)} \equiv D_{1} \neq D_{(02)} \equiv D_{2}, U(0) \equiv U$.

As we already did for the case (A), we modify the graph and obtain figure A2(b). Between vertices 0 and 3, we choose $U\left(x_{03}\right)=U$ and $D\left(x_{03}\right)=\left(\left(\frac{\sqrt{D_{2}}-\sqrt{D_{1}}}{L}\right) x_{03}+\sqrt{D_{1}}\right)^{2} \equiv\left(a x_{03}+b\right)^{2}$. Thus, in the modified graph, $D(x)$ and $U(x)$ are continuous everywhere on the graph.

On the links [10] and [32], the solution of equation (A.2) is still given by (A.3) and (A.5) (with conditions (A.8) and (A.9)). But, on the link [03], (A.4) has to be replaced by

$$
\begin{align*}
& \widehat{S}\left(x_{03}\right)=1 / \gamma+c_{1}\left(a x_{03}+b\right)^{\lambda_{+}}+c_{2}\left(a x_{03}+b\right)^{\lambda_{-}},  \tag{A.17}\\
& \text {with } \quad \lambda_{ \pm}=\frac{1}{2} \pm \frac{1}{2} \sqrt{1+\frac{4 \gamma}{a^{2}}}  \tag{A.18}\\
& a=\frac{\sqrt{D_{2}}-\sqrt{D_{1}}}{L} \tag{A.19}
\end{align*}
$$



Figure A3. (a) The same graph as in figure A1(a) but this time $p_{01} \neq p_{02}$; in $(b), U(x)$ and $D(x)$ are constant on the added links [40] and [03]; $D(x)$ is still continuous on the modified graph.

Standard boundary conditions imply
$a_{2}=b_{2}=-\frac{1}{\gamma} \quad a_{1}=c_{1} D_{1}^{\lambda_{+} / 2}+c_{2} D_{1}^{\lambda_{-} / 2} \quad b_{1}=c_{1} D_{2}^{\lambda_{+} / 2}+c_{2} D_{2}^{\lambda_{-} / 2}$
$a_{1} \phi_{1(01)}^{\prime}+a_{2} \phi_{2(01)}^{\prime}+a\left(c_{1} \lambda_{+} D_{1}^{\left(\lambda_{+}-1\right) / 2}+c_{2} \lambda_{-} D_{1}^{\left(\lambda_{-}-1\right) / 2}\right)=0$
$b_{1} \psi_{1(32)}^{\prime}+b_{2} \psi_{2(32)}^{\prime}-a\left(c_{1} \lambda_{+} D_{2}^{\left(\lambda_{+}-1\right) / 2}+c_{2} \lambda_{-} D_{2}^{\left(\lambda_{-}-1\right) / 2}\right)=0$.
Finally, we get

$$
\begin{align*}
& \frac{\widehat{S}_{(32)}}{\widehat{S}_{(01)}}=\frac{\frac{1}{\gamma}+b_{1}}{\frac{1}{\gamma}+a_{1}} \rightarrow_{L \rightarrow 0} 1,  \tag{A.23}\\
& \frac{\widehat{S}_{(32)}^{\prime}}{\widehat{S}_{(01)}^{\prime}}=\frac{b_{1} \psi_{1(32)}^{\prime}+b_{2} \psi_{2(32)}^{\prime}}{a_{1} \phi_{1(01)}^{\prime}+a_{2} \phi_{2(01)}^{\prime}} \rightarrow_{L \rightarrow 0}-1 . \tag{A.24}
\end{align*}
$$

When $L \rightarrow 0$, we get, for the original graph, $\widehat{S}$ continuous in 0 and

$$
\begin{equation*}
\widehat{S}_{(01)}^{\prime}+\widehat{S}_{(02)}^{\prime}=0 . \tag{A.25}
\end{equation*}
$$

## Appendix B. Backward equation: boundary conditions when $p_{01} \neq p_{02}$

We want to study the case (A) $(U(x)$ discontinuous in 0$)$ for the graph of figure $\mathrm{A} 3(a)$ with, this time, $p_{01} \neq p_{02}$.

Modifying this graph, we obtain a new one, consisting in five vertices, displayed in figure $\mathrm{A} 3(b)$. Vertices 1 and 2 are still absorbing. We set $p_{41}=p_{40}=p_{30}=p_{32}=1 / 2$ but $p_{04} \neq p_{03}\left(p_{04}=p_{01}(\right.$ original graph $)$ and $p_{03}=p_{02}($ original graph $\left.)\right)$.
$U(x)$ (resp. $D(x))$ is set equal to some constant $U($ resp. $D)$ on the added links [40] and [03]. $U(x)$ is discontinuous at vertices 4 and 3 . With the modified graph, we can take advantage of the computations of the boundary conditions performed at the beginning of section 3 and also in appendix A .

The solution of equation (A.2) writes
on the link [14]: $\widehat{S}\left(x_{14}\right)=1 / \gamma+a_{1} \phi_{1}\left(x_{14}\right)+a_{2} \phi_{2}\left(x_{14}\right)$
on the link [40]: $\widehat{S}\left(x_{40}\right)=1 / \gamma+b_{1} \sinh \left(\sqrt{\gamma / D} x_{40}\right)+b_{2} \sinh \left(\sqrt{\gamma / D}\left(L-x_{40}\right)\right)$
on the link [03]: $\widehat{S}\left(x_{03}\right)=1 / \gamma+c_{1} \sinh \left(\sqrt{\gamma / D} x_{03}\right)+c_{2} \sinh \left(\sqrt{\gamma / D}\left(L^{\prime}-x_{03}\right)\right)$
on the link [32]: $\widehat{S}\left(x_{32}\right)=1 / \gamma+d_{1} \psi_{1}\left(x_{32}\right)+d_{2} \psi_{2}\left(x_{32}\right)$.
As before, $\phi_{1,2}$ and $\psi_{1,2}$ are solutions of the equation $\left(L^{+}-\gamma\right) \phi=0$ that satisfy

$$
\begin{array}{llll}
\phi_{1(14)}=0 & \phi_{1(41)}=1 & \phi_{2(14)}=1 & \phi_{2(41)}=0 \\
\psi_{1(32)}=1 & \psi_{1(23)}=0 & \psi_{2(32)}=0 & \psi_{2(23)}=1 \tag{B.6}
\end{array}
$$

The boundary conditions in 0 are given by the beginning of section 3.1. $\widehat{S}$ is continuous and

$$
\begin{equation*}
p_{04} \widehat{S}_{(04)}^{\prime}+p_{03} \widehat{S}_{(03)}^{\prime}=0 \tag{B.7}
\end{equation*}
$$

For vertices 4 and 3, we use the result of appendix A (case (A)). $\widehat{S}$ is again continuous and

$$
\begin{align*}
& \widehat{S}_{(41)}^{\prime} \mathrm{e}^{-U_{1} / D}+\widehat{S}_{(40)}^{\prime} \mathrm{e}^{-U / D}=0  \tag{B.8}\\
& \widehat{S}_{(30)}^{\prime} \mathrm{e}^{-U / D}+\widehat{S}_{(32)}^{\prime} \mathrm{e}^{-U_{2} / D}=0 \tag{B.9}
\end{align*}
$$

We get the relationships
$a_{2}=d_{2}=-\frac{1}{\gamma} \quad a_{1}=b_{2} \sinh (\sqrt{\gamma / D} L) \quad d_{1}=c_{1} \sinh \left(\sqrt{\gamma / D} L^{\prime}\right)$
$b_{1} \sinh (\sqrt{\gamma / D} L)=c_{2} \sinh \left(\sqrt{\gamma / D} L^{\prime}\right)$
$p_{04}\left(-b_{1} \cosh (\sqrt{\gamma / D} L)+b_{2}\right)+p_{03}\left(c_{1}-c_{2} \cosh \left(\sqrt{\gamma / D} L^{\prime}\right)\right)=0$
$\left(a_{1} \phi_{1(41)}^{\prime}+a_{2} \phi_{2(41)}^{\prime}\right) \mathrm{e}^{-U_{1} / D}+\sqrt{\gamma / D}\left(b_{1}-b_{2} \cosh (\sqrt{\gamma / D} L)\right) \mathrm{e}^{-U / D}=0$
$\left(d_{1} \psi_{1(32)}^{\prime}+d_{2} \psi_{2(32)}^{\prime}\right) \mathrm{e}^{-U_{2} / D}-\sqrt{\gamma / D}\left(c_{1} \cosh \left(\sqrt{\gamma / D} L^{\prime}\right)-c_{2}\right) \mathrm{e}^{-U / D}=0$.
Solving and taking the limit $L, L^{\prime} \rightarrow 0$, we are left with

$$
\begin{align*}
& \frac{\widehat{S}_{(32)}}{\widehat{S}_{(41)}}=\frac{\frac{1}{\gamma}+d_{1}}{\frac{1}{\gamma}+a_{1}} \rightarrow_{L, L^{\prime} \rightarrow 0} 1  \tag{B.15}\\
& \frac{\widehat{S}_{(32)}^{\prime}}{\widehat{S}_{(41)}^{\prime}}=\frac{d_{1} \psi_{1(32)}^{\prime}+d_{2} \psi_{2(32)}^{\prime}}{a_{1} \phi_{1(41)}^{\prime}+a_{2} \phi_{2(41)}^{\prime}} \rightarrow_{L, L^{\prime} \rightarrow 0} \mathrm{e}^{\frac{U_{2}-U_{1}}{D}}\left(-\frac{p_{04}}{p_{03}}\right) . \tag{B.16}
\end{align*}
$$

When $L, L^{\prime} \rightarrow 0$, the vertices 3 and 4 move to 0 and we get ${ }^{5}$

$$
\begin{align*}
& \widehat{S}_{(02)}=\widehat{S}_{(01)},  \tag{B.17}\\
& p_{02} \widehat{S}_{(02)}^{\prime} \mathrm{e}^{-U_{(02)} / D(0)}+p_{01} \widehat{S}_{(01)}^{\prime} \mathrm{e}^{-U_{(01)} / D(0)}=0 \tag{B.18}
\end{align*}
$$

[^2]

Figure B1. (a) The same graph as in figure A2(a) but this time $p_{01} \neq p_{02}$; in (b), $U(x)$ and $D(x)$ are constant on the added links [40] and [03]; $U(x)$ is still continuous on the modified graph.

We also observe that

$$
\begin{align*}
& \frac{\widehat{S}_{(03)}}{\widehat{S}_{(30)}} \rightarrow_{L, L^{\prime} \rightarrow 0} 1  \tag{B.19}\\
& \frac{\widehat{S}_{(03)}^{\prime}}{\widehat{S}_{(30)}^{\prime}} \rightarrow_{L, L^{\prime} \rightarrow 0}-1 . \tag{B.20}
\end{align*}
$$

Those relationships will prove useful in appendix C .
The solution for the case (B) (figure $\left.9(a), p_{01} \neq p_{02}\right)$ is immediate.
Indeed, we see that for the modified graph (figure $\mathrm{B} 1(b)$ ) we have, formally, the same solution as equations (B.1)-(B.4) and the same boundary conditions but, this time with $U_{1}=U_{2}=U$. It amounts to drop the exponential factors in (B.8) and in all the equations that follow. Finally, we get that $\widehat{S}$ is continuous and

$$
\begin{equation*}
p_{02} \widehat{S}_{(02)}^{\prime}+p_{01} \widehat{S}_{(01)}^{\prime}=0 \tag{B.21}
\end{equation*}
$$

Moreover, (B.19) and (B.20) still hold.

## Appendix C. Backward equation: general boundary conditions

For the case (A), let us assume that the $p_{\alpha \beta_{i}}$ 's are not all equal. In figure B2(a), where a given vertex $\alpha$ and its $m_{\alpha}$ nearest neighbours are shown, we suppose that $U(x)$ is discontinuous in $\alpha$ and $(D(x)$ is continuous, $D(x) \equiv D(\alpha)$ in $\alpha)$.

In part (b), we slightly modify the graph along the same lines as in appendix B. We add vertices $\mu_{i}$ in such a way that each new link $\left[\mu_{i} \beta_{i}\right]$ is identical to the original link $\left[\alpha \beta_{i}\right]$ (same length, same potential and diffusion constant). Moreover, in the added subgraph (figure B2(b), heavy lines of lengths $L$ ) the potential and the diffusion constant are assumed to be constant (respectively equal to some value $U$ and to $D(\alpha)$ ). So, in the vicinity of $\alpha$, the discontinuities of $U(x)$ will occur at the $\mu_{i}$ 's ( $D(x)$ will be continuous in the same domain). Of course, for the transition probabilities from $\alpha$, we choose $p_{\alpha \mu_{i}}=p_{\alpha \beta_{i}}$. By taking the limit $L \rightarrow 0$, we will recover the original graph.


Figure B2. (a) the vertex $\alpha$ with its nearest neighbours $\beta_{i}, i=1, \ldots, m_{\alpha} ;(b)$ we have added the heavy lines where the potential is set equal to some constant $U$, and the diffusion constant is equal to $D(\alpha)$; for the rest of the graph, nothing has been changed. For further explanations, see the text.

Now, for the small subgraph where $U(x)$ and $D(x)$ are constant, we can take advantage of the result, equation (8), to write

$$
\begin{equation*}
\sum_{i=1}^{m_{\alpha}} p_{\alpha \mu_{i}} P_{\left(\alpha \mu_{i}\right)}^{\prime}=0 . \tag{C.1}
\end{equation*}
$$

Moreover, for the vertex $\mu_{i}$, where $p_{\mu_{i} \alpha}=p_{\mu_{i} \beta_{i}}=1 / 2$, we can use (11) and also (A.16) (directly established in appendix A) to get

$$
\begin{equation*}
\mathrm{e}^{-U / D(\alpha)} P_{\left(\mu_{i} \alpha\right)}^{\prime}+\mathrm{e}^{-U_{\left(\mu_{i} \beta_{i}\right)} / D(\alpha)} P_{\left(\mu_{i} \beta_{i}\right)}^{\prime}=0 . \tag{C.2}
\end{equation*}
$$

Weighting with $p_{\alpha \beta_{i}}\left(\equiv p_{\alpha \mu_{i}}\right)$ and summing over $i$, we deduce

$$
\begin{equation*}
\sum_{i=1}^{m_{\alpha}} p_{\alpha \beta_{i}} \mathrm{e}^{-U_{\left(\mu_{i} \beta_{i}\right)} / D(\alpha)} P_{\left(\mu_{i} \beta_{i}\right)}^{\prime}=-\mathrm{e}^{-U / D(\alpha)}\left(\sum_{i=1}^{m_{\alpha}} p_{\alpha \mu_{i}} P_{\left(\mu_{i} \alpha\right)}^{\prime}\right) \tag{C.3}
\end{equation*}
$$

Now, taking the limit $L \rightarrow 0$, we have from (B.20) (appendix B),

$$
\begin{equation*}
\frac{P_{\left(\mu_{i} \alpha\right)}^{\prime}}{P_{\left(\alpha \mu_{i}\right)}^{\prime}} \rightarrow_{L \rightarrow 0}-1 \tag{C.4}
\end{equation*}
$$

In this limit, the vertex $\mu_{i}$ moves to $\alpha$ and we recover the original graph. Finally, with (C.1), (C.3) and (C.4), we obtain, for the case (A), the boundary condition ${ }^{6}$

$$
\begin{equation*}
\sum_{i=1}^{m_{\alpha}} p_{\alpha \beta_{i}} \mathrm{e}^{-U_{\left(\alpha \beta_{i}\right)} / D(\alpha)} P_{\left(\alpha \beta_{i}\right)}^{\prime}=0 \tag{C.5}
\end{equation*}
$$

Moreover, for the modified graph, $P$ is continuous in $\alpha$ and in $\mu_{i}$. From appendix B, we know that (B.19)

$$
\begin{equation*}
\frac{P_{\left(\mu_{i} \alpha\right)}}{P_{\left(\alpha \mu_{i}\right)}} \rightarrow_{L \rightarrow 0} 1 \tag{С.6}
\end{equation*}
$$

That is enough to conclude that, for the original graph, $P$ is continuous in $\alpha$.
${ }^{6}$ Remark that (C.5) is unchanged when we add a constant to $U(x)$. Now, if we want to consider the case when $U(x)$ and $D(x)$ are both discontinuous at some vertex $\alpha$, we must add, on each link, vertices $\mu_{i}$ and $\mu_{i}^{\prime}$ where either $D(x)$ or $U(x)$ is discontinuous. The resulting boundary condition will depend on the repartition of those additional vertices. Moreover, inconsistencies will appear when we add a constant to $U(x)$. This is why we say that, in our opinion, this problem is ill defined.

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[^0]:    3 It can also occur that $\Phi(x)$ is not well defined, for instance, when $U(x)$ and $D(x)$ are both discontinuous at the same point $x_{1}$. Indeed, $\frac{1}{D\left(x^{\prime}\right)} \frac{\partial U\left(x^{\prime}\right)}{\partial x^{\prime}}$ is then proportional to $\delta\left(x^{\prime}-x_{1}\right) / D\left(x_{1}\right)$; thus, this quantity is not defined if $D(x)$ is discontinuous at $x_{1}$.

[^1]:    ${ }^{4}$ For a graph $\mathcal{G}$ without drift, we could expect, with the same argument, that the average time spent on a part $\mathcal{D}$ of $\mathcal{G}$ would not depend on the diffusion constant on the rest, $\mathcal{G} \backslash \mathcal{D}$, of the graph. This is exactly what can be checked with formulae (39)-(42) of section 4.1 and, also, with formulae (58) and (59) of example 3 of section 4.1.1.

[^2]:    ${ }^{5}$ Recall that $p_{04}=p_{01}$ (original graph) and $p_{03}=p_{02}$ (original graph).

